2nd Workshop on Control of Uncertain Systems: Modelling, Approximation and Design

A workshop to mark the contributions of Keith Glover to the control field

		OGRAMME	
		2 September 2013	
18:30-2	20:30 Opening Reception	Clare College	
		23 September 2013	
Lectur	res will be held in Lecture Room 2,	Department of Engineering, Trumpington St	
09:15	Registration & coffee, LR4		
09:50	Welcome	Prof Steve Young, Pro-Vice-Chancellor	
		Vinter (Imperial College)	
10:00	Brian Anderson (Australian National University)	Formation Control: Uncertain Distances and Nonrobust Behaviour	
10:25	James Sefton (Imperial College London)	Managing Transaction Costs in a Dynamic Trading Strategy	
10:50	Munther Dahleh (MIT)	Resilience of Dynamical Transportation Networks	
	11:	15 COFFEE	
	Chair: Roy	/ Smith (ETH Zürich)	
11:45	Anders Rantzer (Lund University)	Scalable Robustness Analysis Using Integral Quadratic Constraints	
12:10	Michael Cantoni	Robust Stability Analysis for Feedback	
	(University of Melbourne)	Interconnections of Open-loop Unstable Systems	
12:35	Manfred Morari (ETH Zürich)	Fast Model Predictive Control	
13:00 LUNCH – LR4			
	CHAIR: David N	Mayne (Imperial College)	
14:15	Rodolphe Sepulchre (University of Cambridge)	Loop shaping, localised behaviors, and multi- resolution feedback systems	
14:40	Sanjoy Mitter (MIT)	Stochastic Dissipative Systems	
15:05	Sanjay Lall (Stanford University)	Stochastic Control of Multi-player Systems	
	1	15:30 TEA	
		De Moor (KU Leuven)	
16:00	Pablo Iglesias (The Johns Hopkins University)	Control Motifs in the Hypoxic Response of Cells	
16:25	Glenn Vinnicombe (University of Cambridge)	Information Processing and Control in Biological Systems: Some Fundamental Limits	
16:50	Richard Murray (California Institute of Technology)	Feedback and Control in Biological Circuit Design	
17:15	CLOSE	Group photograph	
19:00	Pre-dinner drinks	Trinity College	
19:30	Banquet		

Tuesday 24 September 2013

09:30	Coffee			
		rlane (University of Cambridge)		
10:00	Karl Aström (Lund University)	Loop Shaping from Bode to Glover		
10:25	Rick Hyde (The MathWorks Ltd)	The VAAC Harrier and H-infinity Loop Shaping – What Did We Learn?		
10:50	Gary Balas (University of Minnesota)	Closing the GAP Between Models and Data: A Flight Control Application		
	11:	15 COFFEE		
CHAIR: Ian Postlethwaite (Northumbria University)				
11:45	Pascal Gahinet (The Mathworks Ltd)	Robust Control Meets Nonsmooth Optimization		
12:10	Geir Dullerud (University of Illinois)	Automata-switched systems: Centralized Control and Team Games		
12:35	John Doyle (California Institute of Technology)	Universal Laws and Architectures in Networks: What Would Keith Do?		
13:00 LUNCH – LR4				
CHAIR: Sarah Spurgeon (University of Kent)				
14:15	Lennart Ljung	Will Machine Learning Change the System		
	(Linköping University)	Identification Paradigm?		
14:40	(Linkoping University) Michel Gevers (University of Louvain)	Identification Paradigm? Closed-loop Optimal Experiment Design: Solution Via Moment Extension		
14:40 15:05	Michel Gevers	Closed-loop Optimal Experiment Design: Solution		
-	Michel Gevers (University of Louvain) Dariusz Cieslar (dSPACE Ltd)	Closed-loop Optimal Experiment Design: Solution Via Moment Extension		
-	Michel Gevers (University of Louvain) Dariusz Cieslar (dSPACE Ltd)	Closed-loop Optimal Experiment Design: Solution Via Moment Extension IC Engine Control – the Challenge of Downsizing		
-	Michel Gevers (University of Louvain) Dariusz Cieslar (dSPACE Ltd)	Closed-loop Optimal Experiment Design: Solution Via Moment Extension IC Engine Control – the Challenge of Downsizing 5:30 TEA		
15:05	Michel Gevers (University of Louvain) Dariusz Cieslar (dSPACE Ltd) 1 CHAIR: Jan Maciejow Mathukumalli Vidyasagar	Closed-loop Optimal Experiment Design: Solution Via Moment Extension IC Engine Control – the Challenge of Downsizing 5:30 TEA /ski (University of Cambridge) Near Ideal Behaviour of a Modified Elastic Net		
15:05 16:00	Michel Gevers (University of Louvain) Dariusz Cieslar (dSPACE Ltd) 1 CHAIR: Jan Maciejow Mathukumalli Vidyasagar (University of Texas) Kemin Zhou	Closed-loop Optimal Experiment Design: Solution Via Moment Extension IC Engine Control – the Challenge of Downsizing 5:30 TEA vski (University of Cambridge) Near Ideal Behaviour of a Modified Elastic Net Algorithm in Compressed Sensing A System Approach to Investing in Uncertain		
15:05 16:00 16:25	Michel Gevers (University of Louvain) Dariusz Cieslar (dSPACE Ltd) 1 CHAIR: Jan Maciejow Mathukumalli Vidyasagar (University of Texas) Kemin Zhou (Louisiana State University) Bruce Francis	Closed-loop Optimal Experiment Design: Solution Via Moment Extension IC Engine Control – the Challenge of Downsizing 5:30 TEA /ski (University of Cambridge) Near Ideal Behaviour of a Modified Elastic Net Algorithm in Compressed Sensing A System Approach to Investing in Uncertain Markets		

18:30-20.30 Closing Reception

Sidney Sussex College